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PATENT ABSTRACTS OF JAPAN

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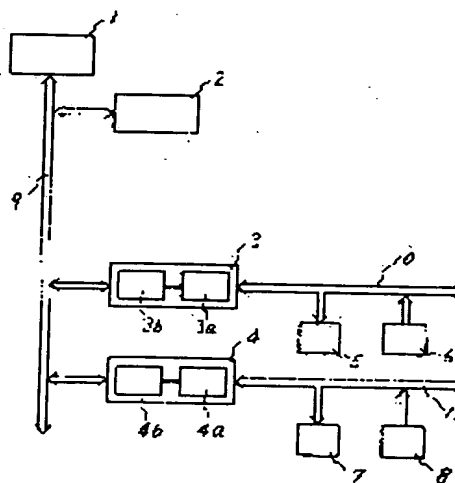
(72)Inventor : KURAKAKE MITSUO

(54) DATA PROCESSING SYSTEM

(57)Abstract:

PURPOSE: To make the change of a program easy, by transferring a control program from an ROM to an RAM of each microprocessor, and eliminating the need for the ROM per a control program of each microprocessor.

CONSTITUTION: A loading unit 2 is started with a power supply applied, the content of an ROM1 is read out and a required control program is stored to RAMs 3b and 4b of microprocessors 3 and 4 via a data bus 9. The loading unit 2 gives a start signal to the microprocessors 3 and 4 after the end of transfer, the microprocessors 3 and 4 respond it and start the operation according to the control program of the RAMs 3b and 4b. On the other hand, since an instruction is given from a main processor via the data bus 9, the microprocessors 3 and 4 control variables 5 and 7 via data buses 10 and 11.



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昭57-176456

⑮ Int. Cl.³
G 06 F 9/24

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庁内整理番号
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発明の数 1
審査請求 未請求

(全 3 頁)

⑭ データ処理方式

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⑰ 特 願 昭56-60965

⑰ 出 願 人 富士通フアナツク株式会社

⑱ 出 願 昭56(1981)4月22日

日野市旭が丘3丁目5番地1

⑲ 発 明 者 鞍掛三津雄

⑲ 代 理 人 弁理士 辻實 外1名

明 細 書

1. 発明の名称

データ処理方式

2. 特許請求の範囲

(1) ランダムアクセスメモリを内蔵したマイクロプロセッサと、該マイクロプロセッサの制御プログラムを収容した不揮発性メモリと、該不揮発性メモリの内容を該マイクロプロセッサに転送するローディングユニットと、これらを接続するデータベースとを有し、該不揮発性メモリに収容された制御プログラムを該ローディングユニットにより該マイクロプロセッサのランダムアクセスメモリに転送することを特徴とするデータ処理方式。

(2) 前記データベースに更に前記マイクロプロセッサを制御するメインプロセッサを接続することを特徴とする特許請求の範囲第(1)項記載のデータ処理方式。

(3) 前記マイクロプロセッサが前記データベースに複数接続されることを特徴とする特許請求の範囲第(1)項又は第(2)項記載のデータ処理方式。

(1)

(4) 前記マイクロプロセッサに制御対象となる入出力ユニットが別のデータベースを介し接続されることを特徴とする特許請求の範囲第(1)項又は第(2)項又は第(3)項記載のデータ処理方式。

(5) 前記ローディングユニットはメモリとマイクロプロセッサで構成されることを特徴とする特許請求の範囲第(1)項又は第(2)項又は第(3)項又は第(4)項記載のデータ処理方式。

(6) 前記制御対象がモータであることを特徴とする特許請求の範囲第(4)項記載のデータ処理方式。

3. 発明の詳細な説明

本発明は、容易に自己の制御プログラムを変更しうるデータ処理方式に関し、特にメモリを内蔵するマイクロプロセッサに好適なデータ処理方式に関する。

近年マイクロプロセッサはその集積度が向上し、又演算速度の向上に伴い各種装置の制御用に盛んに利用されている。かゝる、制御用マイクロプロセッサとしては、制御プログラムを収容しうるメモリを内蔵した1チップ化したマイクロプロセ

(2)

サが便利である。ところで、この様な制御プログラムを内蔵するメモリとしては、電源の供給停止時にも記憶内容を消失しないリードオンリーメモリ（以下ROMと称す）が用いられているが、制御プログラムの変更が容易でない欠点がある。即ち、1チップマイクロプロセッサに内蔵されるROMは、殆んどマスクROM（mask ROM）であり、プログラムの変更が容易でない。尚、イレーザブルROM（Erasable ROM）を内蔵するものもあるが、mask ROMに比べてLSIのチップが大きくなるため、価格、供給、信頼性に問題がある。

以上の点を数値制御システムにおけるサーボモータ制御について具体的に説明する。さて、数値制御システムにおけるサーボモータの制御にマイクロプロセッサを用いる場合には、対象のモータ毎にあるいは、制御方式毎に多数の制御プログラムが用意されている。このためこの中からモータ制御に応じた所定の制御プログラムを選択し、該制御プログラムに基づいてモータを制御する必要がある。このように所定の制御プログラムを選択し

(3)

スメモリ（以下RAMと称す）を内蔵するマイクロプロセッサで構成される。3及び4はマイクロプロセッサで、各々プロセッサ本体3a及び4aと、プロセッサ3a、4aの制御プログラムを格納するためのRAM3b及び4bとで構成される。5及び7はマイクロプロセッサ3、4に制御される出力ユニットであり、この例ではモータを示す。6及び8は入力ユニットであり、この例では、マイクロプロセッサ3、4にモータの状態たとえば回転速度を検知して出力する検知器を示す。9は不揮発性メモリ1、ローディングユニット2、マイクロプロセッサ3、4を相互に接続するメインデータバスであり、数値制御のメインプロセッサにも接続されている。尚、メインプロセッサより移動指令、指令速度などがデータバスを介してマイクロプロセッサ3、4に入力される。10、11はマイクロプロセッサ3、4と、出力ユニット5、7及び入力ユニット6、8とを相互に接続するデータバスである。

次にこれらの動作について説明する。

不揮発性メモリ1には、各種モータの制御のた

(5)

て正しくモータを制御するためにはメモリとして外付けのイレーザブルROM（EROM）を用い、該EROMにモータ或いはモータ制御に応じた制御プログラムを書込むことが考えられるが、1チップ化したプロセッサ以外にROMが必要となるので部品点数が増加し得策でない。又、1つのROMに複数の制御プログラムを収容することも考えられるが、これらの制御プログラムを全て収容するには、ROMの容量が大きくなり、コスト、実装スペースから不利である。

従つて、本発明は、マイクロプロセッサ内部に記憶される制御プログラムを容易に変更しうる新規なデータ処理方式を提供することを目的とするものである。

以下、本発明を実施例により詳細に説明する。

図面は本発明の一実施例ブロック図を示し、図中、1は制御プログラムを格納する不揮発性メモリで、例えばバブルメモリー、ROMで構成される。2は不揮発性メモリ1の内容を読み出し転送するローディングユニットで、ROM又はランダムアクセ

(4)

スの各種の制御プログラムが格納されている。又、マイクロプロセッサ3、4の各々は数値制御における各制御軸毎に用意されていると仮定する。

先づ、電源が投入されると、該電源の投入を検知してローディングユニット2が起動し、ローディングユニット2は自己の制御プログラムに従い不揮発性メモリ1の内容を読み出す。そして、予じめ各マイクロプロセッサ3、4の必要とする制御プログラムがわかっているのので、ローディングユニット2は各マイクロプロセッサ3、4のRAM3b、4bにデータバス9を介し必要とする制御プログラムを転送し、制御プログラムをRAM3b、4bに格納せしめる。

ローディングユニット2は更に転送終了後に各マイクロプロセッサ3、4にスタート信号をデータバス9を介して送り、マイクロプロセッサ3、4は、これに回答し、RAM3b、4bの制御プログラムに従い動作を開始する。一方、図示しない前述のメインプロセッサからデータバス9を介して速度指令、移動数値指令が与えられるから、各マイ

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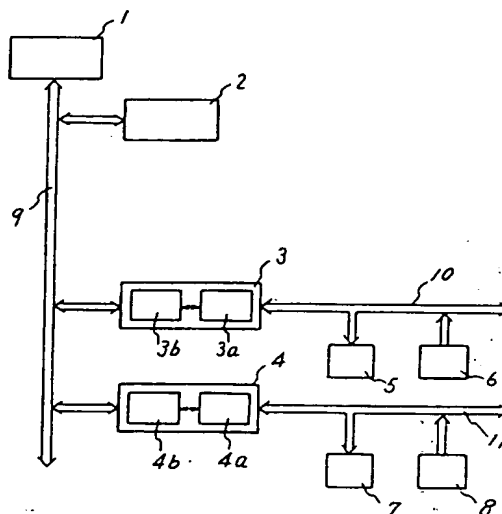
クログプロセッサ 3, 4 はデータバス 10, 11 を介し制御対象であるモータ（出力ユニット）5 及び 7 を制御することになる。

尚、数値制御システムでは、もともと各種パラメータや加工データの収容のために不揮発性メモリを備えているから、前述の不揮発性メモリ 1 を特別設けることなく、このメモリの一部を利用してもよい。

以上の説明では、数値制御システムを例にして説明した、これに限ることなく、他の制御システムにも利用することができる。

以上説明した様、本発明によれば、制御プログラムを格納した不揮発性メモリから各マイクロプロセッサのランダムアクセスメモリに制御プログラムを転送する機構としたので、各マイクロプロセッサに制御プログラム毎に ROM を持つ必要はなく、制御プログラムの変更が容易に達成出来、特に複雑な制御が要求される数値制御システムに極めて有用である。

(7)



4. 図面の簡単な説明

特開昭57-176456 (3)

図面は本発明の一実施例ブロック図を示す。

図中、1…不揮発性メモリ、2…ローディングユニット、3, 4…マイクロプロセッサ、3a, 4a…プロセッサ本体、3b, 4b…ランダムアクセスメモリ、9…データバス。

特許出願人 富士通フナック株式会社

代理人 弁理士 辻 實

外 1 名

(8)

(12)

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published in accordance with Art. 158(3) EPC

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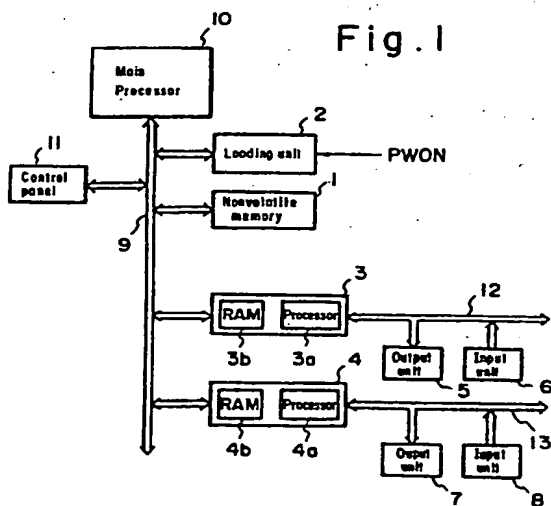
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(84) DATA PROCESSING SYSTEM.

(87) Microprocessors (3, 4) containing random access memories (RAM) (3b, 4b), a non-volatile memory (1) containing the control program of the microprocessors, and a loading unit (2) for transferring the content of the non-volatile memory to the microprocessors are connected via a data bus (9). Since the control program is transferred from the nonvolatile memory to the random access memory in the microprocessors in accordance with the relative relationship between the control program specified on the control panel (11) and the microprocessors when power is applied, the execution control program is facilitated.



DESCRIPTION

DATA PROCESSING SYSTEM

Technical Field:

The present invention relates to a data processing
5 system which can readily change a control program of its
own, and more particularly to a data processing system
which is well-suited for use in a microprocessor having
a built-in memory.

Background Art:

10 In recent year, microprocessors have been extensively
utilized for controlling various apparatuses with enhance-
ment in the density of integration and enhancement in the
operating speed. As such a controlling microprocessor, a
microprocessor in the form of a single chip having a built-
15 in memory capable of receiving a control program is con-
venient. In this regard, a read-only memory (hereinbelow,
termed "ROM"), the stored content of which is not erased
even when the supply of power is terminated, is used as the
aforementioned memory for storing the control program but
20 is disadvantageous in that it is not easy to change the con-
trol program. Mor specifically, most ROMs built in 1-chip
microprocessors are mask ROMs, which cannot readily change
programs. Although erasable ROMs are built in some 1-chip
microprocessors, they have problems in price, supply and re-
25 liability because of larger LSI chips than in the mask ROMs.

The above points will be concretely described with regard to a servomotor control in a numerical control system. When applying a microprocessor to the control of a servomotor in a numerical control system, a large number of control programs are prepared for each motor or each control system which is to be controlled. Therefore, a predetermined control program suited to the motor control must be selected from among the control programs, so as to control the motor on the basis of the selected control program. To the end of selecting the predetermined control program and properly controlling the motor in this manner, it has been considered to employ an erasable ROM (EROM) mounted externally of the microprocessor, as the microprocessor memory, and to write the control program suited to the motor or the motor control, into the EROM. Since, however, the measure of employing the external EROM necessitates the ROM besides the processor fabricated in the form of a single chip, it increases the number of components and is not recommendable.

It has also been considered to accommodate a plurality of control programs in a single ROM. However, the ROM requires a large capacity in order to receive all the control programs. This is disadvantageous from the standpoints of cost and installation space.

Accordingly, the present invention has for its object

- 3 -

to provide a novel data processing system which can readily change a control program stored within a microprocessor.

Disclosure of the Invention:

Disclosed in the present invention is a data processing system comprising a microprocessor having an internal random access memory, a nonvolatile memory in which control programs of the microprocessor are stored, a loading unit which transmits the content of the nonvolatile memory to the microprocessor, and a data bus which connects them, whereby the control program stored in the nonvolatile memory is transmitted to the random access memory of the microprocessor by the loading unit, so as to process data in accordance with this control program. This data processing system is so constructed as to transmit the control program from the nonvolatile memory storing the control programs, to the random access memory of each microprocessor. Therefore, each microprocessor need not be equipped with ROMs for the various control programs and the change in control programs can be achieved with ease. In particular, the system is very useful for a numerical control system in which complicated control is required.

Brief Description of the Drawings:

Figure 1 is a block diagram of an embodiment of the present invention.

Best Mode for Carrying out the Invention:

The present invention will now be described in detail in connection with an embodiment.

Figure 1 shows a block diagram of one embodiment of the present invention. In the figure, numeral 1 designates a nonvolatile memory which stores control programs and which is constructed of, for example, a bubble memory or a ROM. Numeral 2 designates a loading unit which reads out and transmits the content of the nonvolatile memory 1, and which is constructed of a microprocessor having a built-in ROM or random access memory (hereinbelow, termed "RAM"). Microprocessors 3 and 4 are respectively constructed of processors proper 3a and 4a, and RAMs 3b and 4b for storing the control programs of the processors 3a and 4a. Numerals 5 and 7 indicate output units which are controlled by the microprocessors 3, 4, and which are motors in this example. Numerals 6 and 8 indicate input units, which are, in this example, detectors that detect the states of the motors, e.g., the rotating speeds thereof and deliver them to the microprocessors 3, 4. Shown at numeral 9 is a main data bus which connects the nonvolatile memory 1, loading unit 2 and microprocessors 3, 4 to one another, and which is also connected to a main processor 10, a control panel 11, etc. for the numerical control. Move commands, commanded speeds, etc. are

entered from the main processor 10 to the microprocessors 3, 4 through the data bus. Data buses 12, 13 interconnect the microprocessors 3, 4, output units 5, 7 and input units 6, 8.

5 Next, the operations of these constituents will be explained.

In the nonvolatile memory 1, various control programs for controlling the respective motors are stored with identifier codes (for example, names) assigned thereto.

10 In addition, it is assumed that the respective microprocessors 3 and 4 are prepared for the respective controllable axes in the numerical control.

When power from a power supply is introduced (a power "on" signal PWON goes to logical "1"), the loading unit 2 starts upon sensing the introduction power and reads out the content of the nonvolatile memory 1 in accordance with a control program of its own stored in the built-in ROM. The corresponding relationships between the respective microprocessors 3, 4 and the identification numbers, e.g., control program names of the control programs required for these microprocessors are set with the control panel 11 in advance. Accordingly, the loading unit 2 transmits the required control programs to the RAMs 3b, 4b of the respective microprocessors 3, 4 through the data bus 9 while referring to the corresponding relationships and

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20
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stores them in the RAMs 3b, 4b.

The loading unit 2 further sends start signals to the respective microprocessors 3, 4 through the data bus 9 after the end of the above transmission. In response to the signals, the microprocessors 3, 4 start operating in accordance with the control programs of the RAMs 3b, 4b. On the other hand, speed commands and movement value commands are given from the aforementioned main processor through the data bus 9, so that the respective microprocessors 3 and 4 control the motors (output units) 5 and 7 through the data buses 12 and 13.

A numerical control system is originally equipped with a nonvolatile memory in order to store various parameters and machining data. Therefore, a part of this memory can be utilized without specially providing the nonvolatile memory 1 stated before. In addition, the corresponding relationships between the control programs and the microprocessors must be easily settable and changeable. However, once they have been set, they are hardly ever altered. Switches are therefore disposed inside the control panel or the like so as to establish semifixed relationships, in order that the corresponding relationships may be set by means of only the switches. This measure prevents changes in the corresponding relationships and a resulting malfunction as may be caused by

accidental operation attributed to the fact that switches protrude from the outside of the apparatus.

Although a numerical control system has been exemplified in the above description, the invention is not restricted thereto but is also utilizable for other control systems.

Industrial Applicability:

As set forth above, according to the present invention, a data processing system is so constructed as to transmit a control program from a nonvolatile memory storing control programs, to the random access memory of each microprocessor. Therefore, each microprocessor need not be equipped with ROMs for the respective control programs, and a change in control programs can be achieved with ease.

In particular, the system is very useful for a numerical control system in which complicated control is required.

WHAT IS CLAIMED IS:

1. A data processing system characterized by comprising a microprocessor having an internal random access memory, a nonvolatile memory in which control programs of said microprocessor are stored, a loading unit which
5 transmits the content of said nonvolatile memory to said microprocessor, and a data bus which connects them, whereby the control program stored in said nonvolatile memory is transmitted to said random access memory of said microprocessor by said loading unit.

10 2. A data processing system as defined in Claim 1, characterized in that a main processor for controlling said microprocessor is further connected to said data bus.

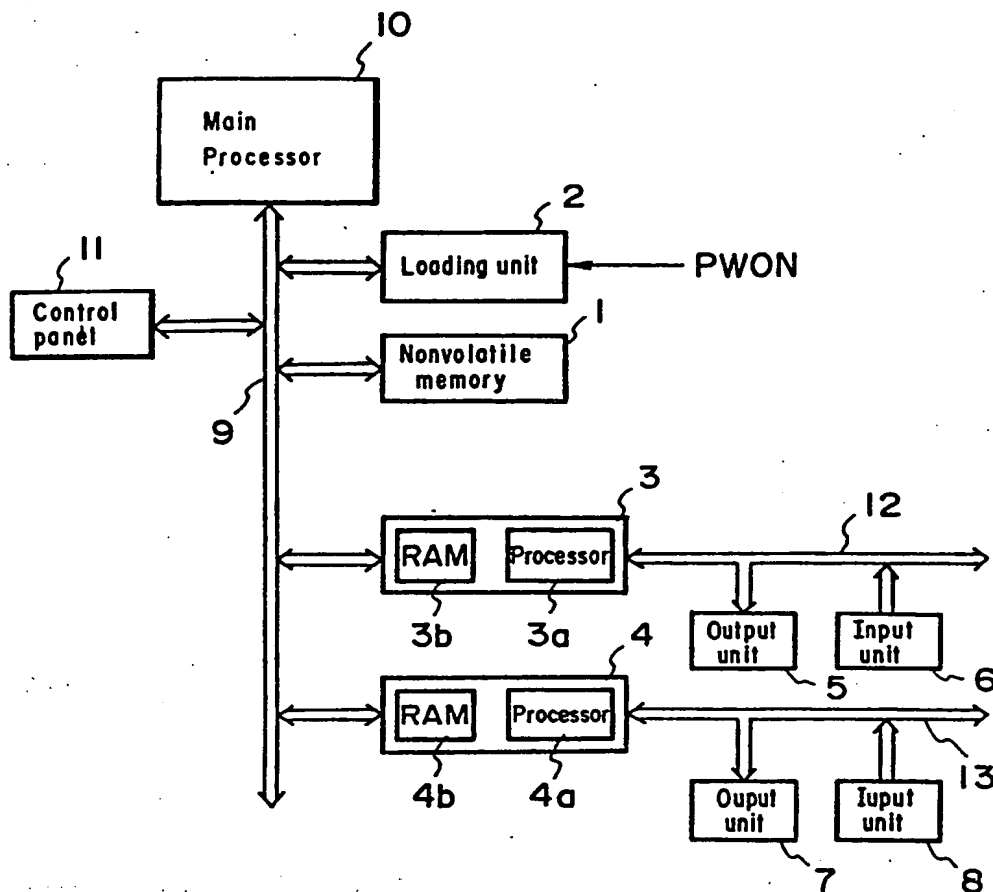
3. A data processing system as defined in Claim 1 or Claim 2, characterized in that a plurality of such micro-
15 processors are connected to said data bus.

4. A data processing system as defined in Claim 1, Claim 2 or Claim 3, characterized in that an input/output unit to be controlled is connected to said microprocessor through another data bus.

20 5. A data processing system as defined in Claim 1, Claim 2, Claim 3 or Claim 4, characterized in that said loading unit is constructed of a memory and a microprocessor.

25 6. A data processing system as defined in Claim 4, characterized in that said unit to be controlled is a motor.

Fig. 1



INTERNATIONAL SEARCH REPORT

0077404

International Application No. PCT/JP 82/00138

I. CLASSIFICATION OF SUBJECT MATTER (If several classification symbols apply, indicate all) *

According to International Patent Classification (IPC) or to both National Classification and IPC

Int Cl³ G06F 3/00, G06F 13/00,
G06F 9/06, G05B 19/02

II. FIELDS SEARCHED

Minimum Documentation Searched *

Classification System

Classification Symbols

IPC

G06F 3/00, G06F 13/00, G06F 9/06
G05B 19/02Documentation Searched other than Minimum Documentation
to the Extent that such Documents are Included in the Fields Searched *

Kokai Jitsuyo Shinkan Koho

1971-1781

III. DOCUMENTS CONSIDERED TO BE RELEVANT **

Category *

Citation of Document, ** with indication, where appropriate, of the relevant passages **

Relevant to Claim No. **

X

JP, A, 50-109635 (Hitachi, Ltd.)

28. August, 1975 (28.08.75)

1-6

X

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6. September, 1979 (06.09.79)

1-6

X

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24. March, 1980 (24.03.80)

1-6

A

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Telephone Public Corp.)

7. June, 1978 (07.06.78)

1-6

* Special categories of cited documents: **

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considered to be of particular relevance"E" earlier document but published on or after the international
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be considered to involve an inventive step when the document
is combined with one or more other such documents, such
combination being obvious to a person skilled in the art

"Z" document member of the same patent family

IV. CERTIFICATION

Date of the Actual Completion of the International Search *

July 20, 1982 (20.07.82)

Date of Mailing of this International Search Report *

July 26, 1982 (26.07.82)

International Searching Authority *

Japanese Patent Office

Signature of Authorized Officer **